

From Last Meeting

Studied Fisher Linear Discrimination

- Mathematics
- “Point Cloud” view
- Likelihood view
- Toy examples
- Extensions (e.g. Principal Discriminant Analysis)

Polynomial Embedding

Aizerman, Braverman and Rozoner (1964) *Automation and Remote Control*, **15**, 821-837.

Motivating idea: extend “scope” of linear discrimination,
by adding “nonlinear components” to data
(better use of name “nonlinear discrimination”????)

E.g. In 1d, “linear separation” splits the domain

$$\{x : x \in \mathcal{X}\}$$

into only 2 parts

Polynomial Embedding (cont.)

But in the “quadratic embedded domain”

$$\{(x, x^2) : x \in \mathcal{R}\} \subset \mathcal{R}^2$$

linear separation can give 3 parts

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- original data space lies in 1d manifold
- very sparse region of \mathcal{R}^2
- curvature of manifold gives better linear separation
- can have *any* 2 break points (2 points \Rightarrow line)

Polynomial Embedding (cont.)

Stronger effects for higher order polynomial embedding:

E.g. for cubic, $\{(x, x^2, x^3) : x \in \mathfrak{R}\} \subset \mathfrak{R}^3$

linear separation can give 4 parts (or fewer)

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- original space lies in 1d manifold, even sparser in \mathfrak{R}^3
- higher d curvature gives improved linear separation
- can have *any* 3 break points (3 points \Rightarrow plane)?
- relatively few “interesting separating planes”

Polynomial Embedding (cont.)

General View: for original data matrix:

$$\begin{pmatrix} x_{11} & & x_{1n} \\ \vdots & \dots & \vdots \\ x_{d1} & & x_{dn} \end{pmatrix}$$

“add rows”:

$$\begin{pmatrix} x_{11} & & x_{1n} \\ \vdots & & \vdots \\ x_{d1} & & x_{dn} \\ x_{11}^2 & \dots & x_{1n}^2 \\ \vdots & & \vdots \\ x_{d1}^2 & & x_{dn}^2 \\ x_{11}x_{21} & & x_{1n}x_{2n} \\ \vdots & & \vdots \end{pmatrix}$$

Polynomial Embedding (cont.)

Fisher Linear Discrimination: Choose Class 1 for \underline{x}^0 when:

$$\underline{x}^{0t} \hat{\Sigma}^{w^{-1}} (\underline{\bar{X}}^{(1)} - \underline{\bar{X}}^{(2)}) \leq \frac{1}{2} (\underline{\bar{X}}^{(1)} + \underline{\bar{X}}^{(2)}) \hat{\Sigma}^{w^{-1}} (\underline{\bar{X}}^{(1)} - \underline{\bar{X}}^{(2)})$$

in *embedded* space.

- image of class boundaries in original space is *nonlinear*
- allows much more *complicated* class regions
- can also do Gaussian Likelihood Ratio (or others)

Polynomial Embedding Toy Examples

E.g. 1: Parallel Clouds

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- PC1 always bad (finds “embedded greatest var.” only)

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- FLD stays good

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- GLR OK discrimination at data, but \exists overfitting problems

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Polynomial Embedding Toy Examples (cont.)

E.g. 2: Two Clouds

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- FLD good, generally improves with higher degree

show PolyEmbed\PEtclFLDcombine.pdf

- GLR mostly good, some overfitting

show PolyEmbed\PEtclGLRcombine.pdf

- $x_1, x_2, x_1^2, x_2^2, x_1 x_2$ similar in shape to x_1, x_2 ???

Polynomial Embedding Toy Examples (cont.)

E.g. 3: Split X

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- FLD rapidly improves with higher degree

show PolyEmbed\Pexd3FLDcombine.pdf

- GLR always good, but never “ellipse around blues”?

show PolyEmbed\Pexd3GLRcombine.pdf

- Should apply ICA first?

Show HDLSS\HDLSSxd3ICA.ps

Polynomial Embedding Toy Examples (cont.)

E.g. 4: Split X, parallel to Axes

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- FLD fine with more embedding

show PolyEmbed\Pexd4FLDcombine.pdf

- GLR OK for all, no overfitting.

show PolyEmbed\Pexd4LGLRcombine.pdf

- never found “ellipse” (maybe “hyperbola” is right?)
- ICA helped FLD (better for lower degree).

Polynomial Embedding Toy Examples (cont.)

E.g. 5: Donut

Show PolyEmbed\PEdonRaw.ps

- FLD: poor for low degree, then good, no overfit

Show PolyEmbed\PEdonFLDcombine.pdf

- GLR: best with no embed, “square shape” for overfitting?

Show PolyEmbed\PEdonGLRcombine.pdf

Polynomial Embedding Toy Examples (cont.)

E.g. 6: Target

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- Similar lessons

Show PolyEmbed\PEtarFLDcombine.pdf, PolyEmbed\PEtarGLRcombine.pdf

- Hoped for better performance from cubic...

Polynomial Embedding (cont.)

Drawback to polynomial embedding:

- too many extra terms create spurious structure
- i.e. have “overfitting”
- **High Dimension Low Sample Size** problems worse

Kernel Machines

Idea: replace polynomials by other “nonlinear functions”

e.g. 1: “sigmoid functions” from neural nets

e.g. 2: “radial basis functions” – Gaussian kernels

Related to “kernel density estimation” (smoothed histogram)

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Kernel Machines (cont.)

Radial basis functions: at some “grid points” $\underline{g}_1, \dots, \underline{g}_k$,

For a “bandwidth” (i.e. standard deviation) σ ,

Consider (d dim'al) functions: $\varphi_\sigma(\underline{x} - \underline{g}_1), \dots, \varphi_\sigma(\underline{x} - \underline{g}_k)$

Replace data matrix with:

$$\begin{pmatrix} \varphi_\sigma(\underline{X}_1 - \underline{g}_1) & \dots & \varphi_\sigma(\underline{X}_n - \underline{g}_1) \\ \vdots & \dots & \vdots \\ \varphi_\sigma(\underline{X}_1 - \underline{g}_k) & \dots & \varphi_\sigma(\underline{X}_n - \underline{g}_k) \end{pmatrix}$$

Kernel Machines (cont.)

For discrimination: work in radial basis function domain,

With new data vector \underline{X}_0 represented by:

$$\begin{pmatrix} \varphi_{\sigma}(\underline{X}_0 - \underline{g}_1) \\ \vdots \\ \varphi_{\sigma}(\underline{X}_0 - \underline{g}_1) \end{pmatrix}$$

Kernel Machines (cont.)

Toy Examples:

E.g. 1: Parallel Clouds – good at data, poor outside

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E.g. 2: Two Clouds – Similar result

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E.g. 3: Split X – OK at data, strange outside

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Kernel Machines (cont.)

E.g. 4: Split X, parallel to Axes – similar ideas

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E.g. 5: Donut – mostly good (slight mistake for one kernel)

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E.g. 6: Target – much better than other examples

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Main lesson: generally good in regions with data,
unpredictable results where data are sparse

Kernel Machines (cont.)

E.g. 7: Checkerboard

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- Kernel embedding is excellent

Show PolyEmbed\PechbFLDe7.ps

- Other polynomials lack flexibility

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- Lower degree is worse

Kernel Machines (cont.)

Note: Gaussian Likelihood Ratio had frequent numerical failure

Important point for kernel machines:

High Dimension Low Sample Size problems get worse

This is motivation for “Support Vector Machines”

Kernel Machines (cont.)

∃ generalizations of this idea to other types of analysis,
and some clever computational ideas.

E.g. “Kernel based, nonlinear Principal Components Analysis”

Schölkopf, Smola and Müller (1998) “Nonlinear component analysis as a kernel eigenvalue problem”, *Neural Computation*, **10**, 1299-1319.

Support Vector Machines

Classical References:

Vapnik (1982) *Estimation of dependences based on empirical data*, Springer (Russian version, 1979)

Boser, Guyon & Vapnik (1992) in *Fifth Annual Workshop on Computational Learning Theory*, ACM.

Vapnik (1995) *The nature of statistical learning theory*, Springer.

Recommended tutorial:

Burges (1998) A tutorial on support vector machines for pattern recognition, *Data Mining and Knowledge Discovery*, **2**, 955-974, see also web site:

<http://citeseer.nj.nec.com/burges98tutorial.html>

Support Vector Machines (cont.)

Motivation: **High Dimension Low Sample Size** discrimination

(e.g. from doing a nonlinear embedding)

∃ a tendency towards major *over-fitting* problems

Toy Example:

In 1st dimension: **Class 1:** $N(2,0.8)$ **Class 2:** $N(-2,0.8)$
($n = 20$ of each, and threw in 4 “outliers”)

In dimensions $2, \dots, d$: independent $N(0,1)$

Support Vector Machines (cont.)

Toy Example: for linear discrimination:

Top: Proj'n onto (2-d) subspace generated by 1st unit vector (- -) and Discrimination direction vector (----) (shows angle)

For “reproducible (over new data sets) discrimination”:

Want these “near each other”, i.e. small angle

Bottom: 1-d projections, and smoothed histograms

Support Vector Machines (cont.)

Lessons from Fisher Linear Discrimination Toy Example:

- Great angle for $d = 1$, but substantial overlap
- OK angle for $d = 2, \dots, 10$, still significant overlap
- Angle gets very bad for $d = 11, \dots, 18$, but overlap declines
- No overlap for $d \geq 23$ (perfect discrimination!?!?)
- Completely nonreproducible (with new data)
- Thus useless for real discrimination

Support Vector Machines (cont.)

Main Goal of Support Vector Machines:

Achieve a trade off between:

Discrimination quality for data at hand

vs.

Reproducibility with new data

Approaches:

1. Regularization (bound on “generaliz’n”, via “complexity”)
2. Quadratic Programming (general’n of Linear Prog.)