

Course Overview

Finished heuristic look at:

1. Understanding population structure – PCA
 - Toy examples
 - Cornea data - robustness

2. Discrimination (Classification)
 - Fisher Linear Discrimination
 - Corpus Callosum Data – Orthogonal subspace projection

Now take careful look at mathematics - numerics

Linear Algebra Review

Vector Space:

- set of “vectors”, \underline{x} ,
- and “scalars” (coefficients), a
- “closed” under “linear combination” ($\sum_i a_i \underline{x}_i$ in space)

- e.g. $\mathfrak{R}^d = \left\{ \underline{x} = \begin{pmatrix} x_1 \\ \vdots \\ x_d \end{pmatrix} : x_1, \dots, x_d \in \mathfrak{R}^d \right\}$, “ d dim Euclid’n space”

Linear Algebra Review, (cont.)

Subspace:

- subset that is again a vector space
- i.e. closed under linear combination
- e.g. lines through the origin
- e.g. planes through the origin
- e.g. subspace “generated by” a set of vectors
(all linear combos of them = containing hyperplane)

Linear Algebra Review, (cont.)

Basis of subspace: set of vectors that:

- “span”, i.e. everything is a linear combo of them
- are “linearly independent”, i.e. linear combo is unique

- e.g. \mathcal{R}^d “unit vector basis” $\left\{ \begin{pmatrix} 1 \\ 0 \\ \vdots \\ 0 \end{pmatrix}, \begin{pmatrix} 0 \\ 1 \\ \vdots \\ 0 \end{pmatrix}, \dots, \begin{pmatrix} 0 \\ \vdots \\ 0 \\ 1 \end{pmatrix} \right\}$

- e.g. $\begin{pmatrix} x_1 \\ x_2 \\ \vdots \\ x_d \end{pmatrix} = x_1 \begin{pmatrix} 1 \\ 0 \\ \vdots \\ 0 \end{pmatrix} + x_2 \begin{pmatrix} 0 \\ 1 \\ \vdots \\ 0 \end{pmatrix} + \dots + x_d \begin{pmatrix} 0 \\ \vdots \\ 0 \\ 1 \end{pmatrix}$

Linear Algebra Review, (cont.)

Basis Matrix, of subspace of \mathfrak{R}^d

Given a basis, $\underline{v}_1, \dots, \underline{v}_n$, create “matrix of columns”:

$$B = \left(\underline{v}_1 \quad \dots \quad \underline{v}_n \right) = \begin{pmatrix} v_{11} & \dots & v_{n1} \\ \vdots & \dots & \vdots \\ v_{1d} & \dots & v_{nd} \end{pmatrix}_{d \times n}$$

Then “linear combo” is a matrix multiplication:

$$\sum_{i=1}^n a_i \underline{v}_i = B \underline{a} \quad \text{where} \quad \underline{a} = \begin{pmatrix} a_1 \\ \vdots \\ a_n \end{pmatrix}$$

Often useful to check sizes: $d \times 1 = (d \times n) \leftrightarrow (n \times 1)$

Linear Algebra Review, (cont.)

Dimension of subspace (a notion of “size”):

- number of elements in a basis (unique)
- $\dim(\mathcal{R}^d) = d$ (use basis above)
- e.g. dim of a line is 1
- e.g. dim of a plane is 2
- dimension is “degrees of freedom”

Linear Algebra Review, (cont.)

Norm of a vector:

- in \mathfrak{R}^d , $\|\underline{x}\| = \left(\sum_{j=1}^d x_j^2 \right)^{1/2} = (\underline{x}^t \underline{x})^{1/2}$

- Idea: “length” of the vector

- But recall strange properties for high d ,
e.g. “length of diagonal of unit cube” = \sqrt{d}

- “length normalized vector”: $\frac{\underline{x}}{\|\underline{x}\|}$

(has length one, this is on surface of unit sphere)

- get “distance” as: $d(\underline{x}, \underline{y}) = \|\underline{x} - \underline{y}\| = \sqrt{(\underline{x} - \underline{y})^t (\underline{x} - \underline{y})}$

Linear Algebra Review, (cont.)

Inner (dot, scalar) product:

- for vectors \underline{x} and \underline{y} , $\langle \underline{x}, \underline{y} \rangle = \sum_{j=1}^d x_j y_j = \underline{x}^t \underline{y}$

- related to norm, via $\|\underline{x}\| = \sqrt{\langle \underline{x}, \underline{x} \rangle} = \sqrt{\underline{x}^t \underline{x}}$

- measures “angle between \underline{x} and \underline{y} ” as:

$$\text{angle}(\underline{x}, \underline{y}) = \cos^{-1} \left(\frac{\langle \underline{x}, \underline{y} \rangle}{\|\underline{x}\| \cdot \|\underline{y}\|} \right) = \cos^{-1} \left(\frac{\underline{x}^t \underline{y}}{\sqrt{\underline{x}^t \underline{x} \cdot \underline{y}^t \underline{y}}} \right)$$

- key to “orthogonality”, i.e. “perpendicularity”:

$$\underline{x} \perp \underline{y} \quad \text{if and only if} \quad \langle \underline{x}, \underline{y} \rangle = 0$$

Linear Algebra Review, (cont.)

Orthonormal basis $\underline{v}_1, \dots, \underline{v}_n$:

- All ortho to each other, i.e. $\langle \underline{v}_i, \underline{v}_{i'} \rangle = 0$, for $i \neq i'$

- All have length 1, i.e. $\langle \underline{v}_i, \underline{v}_i \rangle = 1$, for $i = 1, \dots, n$

- “Spectral Representation”: $\underline{x} = \sum_{i=1}^n a_i \underline{v}_i$ where $a_i = \langle \underline{x}, \underline{v}_i \rangle$

check:
$$\langle \underline{x}, \underline{v}_i \rangle = \left\langle \sum_{i'=1}^n a_{i'} \underline{v}_{i'}, \underline{v}_i \right\rangle = \sum_{i'=1}^n a_{i'} \langle \underline{v}_{i'}, \underline{v}_i \rangle = a_i$$

- Matrix notation: $\underline{x} = B\underline{a}$ where $\underline{a}^t = \underline{x}^t B$ i.e. $\underline{a} = B^t \underline{x}$

- \underline{a} is called “transform (e.g. Fourier, wavelet) of \underline{x} ”

Linear Algebra Review, (cont.)

Parseval identity, for \underline{x} in subsp. gen'd by o. n. basis $\underline{v}_1, \dots, \underline{v}_n$:

- $\|\underline{x}\|^2 = \sum_{i=1}^n \langle \underline{x}, \underline{v}_i \rangle^2 = \sum_{i=1}^n a_i^2 = \|\underline{a}\|^2$
- Pythagorean theorem
- “Decomposition of Energy”
- ANOVA - sums of squares
- Transform, \underline{a} , has same length as \underline{x} , i.e. “rotation in \mathfrak{R}^d ”

Linear Algebra Review, (cont.)

Projection of a vector \underline{x} onto a subspace V :

- Idea: member of V that is closest to \underline{x} (i.e. “approx’n”)
- Find $P_V \underline{x} \in V$ that solves: $\min_{\underline{v} \in V} \|\underline{x} - \underline{v}\|$ (“least squares”)
- For inner product (Hilbert) space: exists and is unique
- General solution in \mathfrak{R}^d : for basis matrix B_V
$$P_V \underline{x} = B_V (B_V^t B_V)^{-1} B_V^t \underline{x}$$
- So “proj’n operator” is “matrix mult’n”: $P_V = B_V (B_V^t B_V)^{-1} B_V^t$
(thus projection is another linear operation)
(note same operation underlies “least squares”)

Linear Algebra Review, (cont.)

Projection using orthonormal basis $\underline{v}_1, \dots, \underline{v}_n$:

- Basis matrix is “orthonormal”: $B_V^t B_V = I_{n \times n}$

$$\begin{pmatrix} \underline{v}_1^t \\ \vdots \\ \underline{v}_n^t \end{pmatrix} (\underline{v}_1 \quad \dots \quad \underline{v}_n) = \begin{pmatrix} \langle \underline{v}_1, \underline{v}_1 \rangle & \dots & \langle \underline{v}_1, \underline{v}_n \rangle \\ \vdots & \ddots & \vdots \\ \langle \underline{v}_n, \underline{v}_1 \rangle & \dots & \langle \underline{v}_n, \underline{v}_n \rangle \end{pmatrix} = \begin{pmatrix} 1 & \dots & 0 \\ \vdots & \ddots & \vdots \\ 0 & \dots & 1 \end{pmatrix}$$

- So $P_V \underline{x} = B_V (B_V^t \underline{x}) = \text{Recon}(\text{Coeffs of } \underline{x} \text{ “in } V \text{ dir’n”})$

- For “orthogonal complement”, V^\perp ,

$$\underline{x} = P_V \underline{x} + P_{V^\perp} \underline{x} \quad \text{and} \quad \|\underline{x}\|^2 = \|P_V \underline{x}\|^2 + \|P_{V^\perp} \underline{x}\|^2$$

- Parseval inequality: $\|\underline{x}\|^2 \leq \|P_V \underline{x}\|^2 = \sum_{i=1}^n \langle \underline{x}, \underline{v}_i \rangle^2 = \sum_{i=1}^n a_i^2 = \|\underline{a}\|^2$

Linear Algebra Review, (cont.)

Eigenvalue Decomposition:

For a (symmetric) square matrix $X_{d \times d}$

Find a diagonal matrix $D = \begin{pmatrix} \lambda_1 & \cdots & 0 \\ \vdots & \ddots & \vdots \\ 0 & \cdots & \lambda_d \end{pmatrix}$

And an orthonormal matrix $B_{d \times d}$ (i.e. $B^t \cdot B = B \cdot B^t = I_{d \times d}$)

So that: $X \cdot B = B \cdot D$, i.e. $X = B \cdot D \cdot B^t$

Linear Algebra Review, (cont.)

Intuition behind Eigenvalue Decomposition:

For X a “linear transformation” (via matrix multiplication)

- $X \cdot \underline{v} = (B \cdot D \cdot B^t) \cdot \underline{v} = B \cdot (D \cdot (B^t \cdot \underline{v}))$
- First “rotate”
- Second “rescale coordinate axes (by λ s)”
- Third “invert rotation”

For X a basis matrix of \mathfrak{R}^d , B gives “rotation to make parallel to coordinate axes”

Linear Algebra Review, (cont.)

Computation of Eigenvalue Decomposition:

- Details too complex to spend time here
- A “primitive” of good software packages
- Eigenvalues $\lambda_1, \dots, \lambda_d$ are unique
- Columns of $B = (\underline{v}_1 \ \cdots \ v_d)$ are called “eigenvectors”
- Eigenvectors are “ λ -stretched” by X :
$$X \cdot \underline{v}_i = \lambda_i \cdot \underline{v}_i$$

Linear Algebra Review, (cont.)

Eigenvalue Decomposition solves matrix problems:

- Inversion: $X^{-1} = B \cdot \begin{pmatrix} \lambda_1^{-1} & \cdots & 0 \\ \vdots & \ddots & \vdots \\ 0 & \cdots & \lambda_d^{-1} \end{pmatrix} \cdot B^t$
- Square Root: $X^{1/2} = B \cdot \begin{pmatrix} \lambda_1^{1/2} & \cdots & 0 \\ \vdots & \ddots & \vdots \\ 0 & \cdots & \lambda_d^{1/2} \end{pmatrix} \cdot B^t$
- $\text{rank}(X) = \#\{\lambda_i : \lambda_i \neq 0\}$
- X is positive (semi) definite \Leftrightarrow all $\lambda_i > (\geq) 0$

Multivariate Probability Review

Given a “random vector”, $\underline{X} = \begin{pmatrix} X_1 \\ \vdots \\ X_n \end{pmatrix}$,

A “center” of the dist’n is the mean vector, $\underline{\mu} = E \underline{X} = \begin{pmatrix} EX_1 \\ \vdots \\ EX_n \end{pmatrix}$

A “measure of spread” is the covariance matrix:

$$\Sigma = \text{cov}(X) = \begin{pmatrix} \text{var}(X_1) & \cdots & \text{cov}(X_1, X_n) \\ \vdots & \ddots & \vdots \\ \text{cov}(X_n, X_1) & \cdots & \text{var}(X_n) \end{pmatrix}$$

Multivariate Probability Review, (cont.)

Covariance matrix:

- Nonegative Definite (since all variances are ≥ 0)
- Provides “elliptical summary of distribution”
- Calculated via “outer product”:

$$\Sigma = \text{cov}(X) = E \left[\begin{array}{ccc} (X_1 - \mu_1)(X_1 - \mu_1) & \cdots & (X_1 - \mu_1)(X_n - \mu_n) \\ \vdots & \ddots & \vdots \\ (X_n - \mu_n)(X_1 - \mu_1) & \cdots & (X_n - \mu_n)(X_n - \mu_n) \end{array} \right] =$$

$$\Sigma = E(\underline{X} - \underline{\mu})(\underline{X} - \underline{\mu})^t$$

Multivariate Probability Review, (cont.)

Empirical versions:

Given a “random sample” $\underline{X}_1, \dots, \underline{X}_n$,

Estimate the “theoretical mean” $\underline{\mu}$, with the “sample mean”:

$$\underline{\hat{\mu}} = \underline{\bar{X}} = \begin{pmatrix} \bar{X}_1 \\ \vdots \\ \bar{X}_d \end{pmatrix} = \frac{1}{n} \sum_{i=1}^n \underline{X}_i$$